

Automating the workmanship works that involve contacts with objects

Realtime robot operation

➤ Operate robots freely with high-speed response

- The robot's highly responsive control functions allow operators to materialize their thoughts in real time.

Transmitting force and sense of touch to remote locations



➤ Sense of touch reproduced by Real Haptics®

- Operators can perform manual labor while realistically feeling the forces felt by the robot as it touches an object.

3D real user interface

➤ Reproduce the conditions of remote locations in real-time virtual reality

- Reproduction of the on-site process in real time enables you to work remotely while feeling like you're actually there.

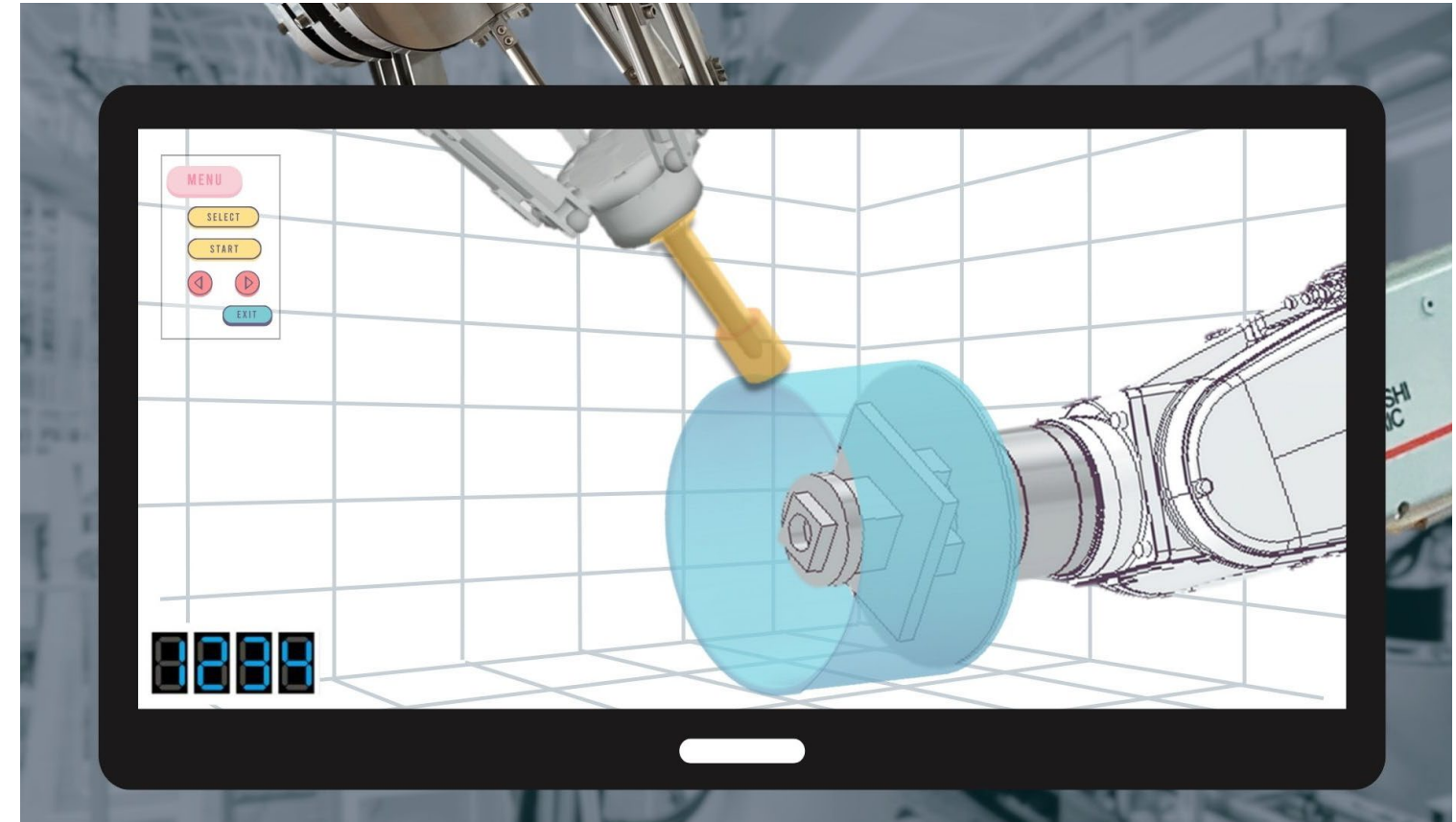


IMAGE Proc.



MELFA



MELSEC iQ-R



MELSERVO